

1 The overall effect of the two successive reflections is the mapping

$$\mathbf{r} \rightarrow \mathbf{r} - 2\mathbf{e}_1 \mathbf{e}_1 \cdot \mathbf{r} \rightarrow (\mathbf{r} - 2\mathbf{e}_1 \mathbf{e}_1 \cdot \mathbf{r}) - 2\mathbf{e}_2 \mathbf{e}_2 \cdot (\mathbf{r} - 2\mathbf{e}_1 \mathbf{e}_1 \cdot \mathbf{r}),$$

that is: $\mathbf{r} \rightarrow \mathbf{r} - 2\mathbf{e}_1 \mathbf{e}_1 \cdot \mathbf{r} - 2\mathbf{e}_2 \mathbf{e}_2 \cdot \mathbf{r} + 4\mathbf{e}_2 \mathbf{e}_2 \cdot \mathbf{e}_1 \mathbf{e}_1 \cdot \mathbf{r}$. In the case of $\mathbf{e}_1 = \pm \mathbf{e}_2$, the second reflection undoes the first and the overall mapping is the identity.

(a) We need to verify that $\mathbf{e}_1 \times \mathbf{e}_2$ is mapped onto itself, which is immediate.

(b) We take a vector that is perpendicular to the rotation axis, such as \mathbf{e}_1 . This is mapped onto $-\mathbf{e}_1 + 2\mathbf{e}_2 \mathbf{e}_2 \cdot \mathbf{e}_1$, so that

$$\cos \phi = \mathbf{e}_1 \cdot (-\mathbf{e}_1 + 2\mathbf{e}_2 \mathbf{e}_2 \cdot \mathbf{e}_1) = -1 + 2(\mathbf{e}_1 \cdot \mathbf{e}_2)^2 = -1 + 2(\cos \alpha)^2 = \cos(2\alpha).$$

This gives $\phi = 2\alpha$ or $\phi = -2\alpha$.

2 We use (2.2.140) for $\gamma = 0$, $\omega = \omega_0$, $x_0 = 0$ and $F(t') = mg$,

$$x(t) = v_0 \frac{\sin(\omega_0 t)}{\omega_0} + g \int_0^t dt' \frac{\sin(\omega_0(t-t'))}{\omega_0} = v_0 \frac{\sin(\omega_0 t)}{\omega_0} + \frac{g}{\omega_0^2} [1 - \cos(\omega_0 t)],$$

where we need to find v_0 such that $\dot{x}(T) = 0$. This requirement reads

$$v_0 \cos(\omega_0 T) + \frac{g}{\omega_0} \sin(\omega_0 T) = 0 \quad \text{or} \quad v_0 = -\frac{g}{\omega_0} \tan(\omega_0 T),$$

so that we have

$$x(t) = \frac{g}{\omega_0^2} - \frac{g}{\omega_0^2} \frac{\sin(\omega_0 t) \sin(\omega_0 T) + \cos(\omega_0 t) \cos(\omega_0 T)}{\cos(\omega_0 T)} = \frac{g}{\omega_0^2} - \frac{g}{\omega_0^2} \frac{\cos(\omega_0(T-t))}{\cos(\omega_0 T)}$$

and

$$\dot{x}(t) = -\frac{g}{\omega_0} \frac{\sin(\omega_0(T-t))}{\cos(\omega_0 T)}$$

at intermediate times.

3

- (a) For $E > 0$ the motion is unbounded; for $0 > E > -E_0$ we have motion between two turning points; there is no energy range with motion bounded by one turning point; $E < -E_0$ is not possible.
- (b) For $E = V(\pm a) = -E_0/[\cosh(ka)]^2$, (3.1.19) gives

$$\begin{aligned} T(E) &= 2 \int_{-a}^a dx \left[\frac{2E_0}{m} \left(\frac{1}{\cosh(kx)^2} - \frac{1}{\cosh(ka)^2} \right) \right]^{-1/2} \\ &= \sqrt{\frac{2m}{E_0}} \int_{-a}^a dx \frac{\cosh(ka) \cosh(kx)}{\sqrt{\cosh(ka)^2 - \cosh(kx)^2}} \\ &= \sqrt{\frac{2m}{E_0}} \frac{\cosh(ka)}{k} \underbrace{\int_{-a}^a dx \frac{k \cosh(kx)}{\sqrt{\sinh(ka)^2 - \sinh(kx)^2}}}_{=\pi}, \end{aligned}$$

where the integral can be evaluated with the substitution $\sinh(kx) = \sinh(ka) \sin \varphi$. With $\cosh(ka) = \sqrt{-E_0/E}$, the final answer is

$$T(E) = \frac{\pi}{k} \sqrt{\frac{2m}{-E}} \quad \text{for } -E_0 < E < 0.$$

4

- (a) The curl of \mathbf{F} is

$$\begin{aligned} \nabla \times \mathbf{F}(\mathbf{r}) &= \underbrace{\nabla f_1(r)}_{=\frac{1}{r}f_1'(r)\mathbf{r}} \times \mathbf{a} + \underbrace{\nabla f_2(r)}_{=\frac{1}{r}f_2'(r)\mathbf{r}} \times (\mathbf{a} \cdot \mathbf{r} \mathbf{r}) + f_2(r) \underbrace{(\nabla \mathbf{a} \cdot \mathbf{r})}_{=\mathbf{a}} \times \mathbf{r} \\ &+ f_2(r) \mathbf{a} \cdot \mathbf{r} \underbrace{\nabla \times \mathbf{r}}_{=0} = \left(\frac{1}{r}f_1'(r) - f_2(r) \right) \mathbf{r} \times \mathbf{a}. \end{aligned}$$

For a conservative force, we need a vanishing curl, which requires $f_2(r) = \frac{1}{r}f_1'(r)$.

- (b) Now, for $f_2(r) = \frac{1}{r}f_1'(r)$, we have

$$\mathbf{F}(\mathbf{r}) = f_1(r) \mathbf{a} + \frac{1}{r}f_1'(r) \mathbf{a} \cdot \mathbf{r} \mathbf{r} = f_1(r) \nabla(\mathbf{a} \cdot \mathbf{r}) + \mathbf{a} \cdot \mathbf{r} \nabla f_1(r) = \nabla(f_1(r) \mathbf{a} \cdot \mathbf{r}),$$

so that $V(\mathbf{r}) = -f_1(r) \mathbf{a} \cdot \mathbf{r}$ is a potential energy for this conservative force.