

Tutorial for Chapter 1

- 1) Memorize Maxwell's equations in general form and in electrically neutral, non-magnetic materials and be prepared to reproduce them from memory on an exam.
- 2) Define that $\mathbf{r} = (\hat{x} + 2\hat{y} - 3\hat{z})$ m and $\mathbf{r}_0 = (-\hat{x} + 3\hat{y} + 2\hat{z})$ m, (i) find the magnitude of \mathbf{r} , (ii) find the magnitude of $\mathbf{r} - \mathbf{r}_0$, and (iii) find the angle between \mathbf{r} and \mathbf{r}_0 .
- 3) Define that $\mathbf{F}(\mathbf{r}) = xy\hat{x} + (1-yz)\hat{y} + xz^2\hat{z}$, (i) find the divergence of $\mathbf{F}(\mathbf{r})$, and (ii) find the curl of $\mathbf{F}(\mathbf{r})$.
- 4) Define that $f(x, y, z) = 1/(x^2 + y^2 + z^2)$, find the derivative of $f(x, y, z)$.
- 5) By applying the same mathematical trick described in Section 1.7, derive the wave equation for the magnetic field \mathbf{B} in vacuum (i.e. $\mathbf{J}_{\text{free}} = 0$ and $\mathbf{P} = 0$).
- 6) Check that $\mathbf{E}(\mathbf{r} \cdot \hat{\mathbf{u}} - ct + \phi)$ satisfies Eq. (1.32), where \mathbf{E} is an arbitrary functional form, $\hat{\mathbf{u}}$ is a unit vector, ϕ is a constant phase, and c is a constant speed.
- 7) Verify that a summation of waves with different unit vectors $\sum_i \mathbf{E}_i(\mathbf{r} \cdot \hat{\mathbf{u}}_i - ct + \phi_i)$ is also a solution of Eq. (1.32).
- 8) Suppose that an electric field is given by $\mathbf{E}(\mathbf{r}, t) = \mathbf{E}_0 \cos(\mathbf{k} \cdot \mathbf{r} - \omega t + \phi)$, where \mathbf{k} is a constant wave vector perpendicular to \mathbf{E}_0 , ω is a constant angular frequency, and ϕ is a constant phase.
Show that $\mathbf{B}(\mathbf{r}, t) = \mathbf{k} \times \mathbf{E}_0 / \omega \cos(\mathbf{k} \cdot \mathbf{r} - \omega t + \phi)$ is consistent with Eq. (1.3).
- 9) Memorize the wave equations Eq. 1.31 and Eq. 1.32, and be prepared to reproduce them from memory on an exam.
- 10) Use Microsoft Excel software to produce several snapshots of a wave: $\cos[(x - ct)2\pi/\lambda]$ with $c = 3 \times 10^8$ m/s and $\lambda = 5 \times 10^{-7}$ m, similar to Figure 1.7.

$$2. i) |\vec{r}| = \sqrt{1^2 + 2^2 + (-3)^2} = \sqrt{14} \text{ m}$$

$$ii) |\vec{r} - \vec{r}_0| = \sqrt{(1+1)^2 + (2-3)^2 + (-3-2)^2} = \sqrt{30} \text{ m}$$

$$iii) |\vec{r}_0| = \sqrt{(-1)^2 + 3^2 + 2^2} = \sqrt{14}$$

$$|\vec{r}| \cdot |\vec{r}_0| = (1)(-1) + (2 \times 3) + (-3) \times 2 = -1$$

$$= |\vec{r}| |\vec{r}_0| \cos \theta$$

$$\cos \theta = \frac{-1}{\sqrt{14} \sqrt{14}}$$

$$\theta = \cos^{-1} \left[\frac{-1}{14} \right]$$

$$3. i) \nabla \cdot \vec{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z}$$

$$= y - z + 2xz = y + z(2x-1)$$

$$ii) \nabla \times \vec{F} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix} = \left(\frac{\partial F_z}{\partial y} - \frac{\partial F_y}{\partial z} \right) \hat{x}^1$$

$$+ \left(\frac{\partial F_x}{\partial z} - \frac{\partial F_z}{\partial x} \right) \hat{y}^1 + \left(\frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} \right) \hat{z}^1$$

$$= (0 - (-y)) \hat{x}^1 + [0 - z^2] \hat{y}^1 + [0 - x] \hat{z}^1$$

$$= y \hat{x}^1 + (-z^2) \hat{y}^1 + (-x) \hat{z}^1$$

$$\begin{aligned}
 4. \quad \nabla f &= \frac{\partial f}{\partial x} \hat{x} + \frac{\partial f}{\partial y} \hat{y} + \frac{\partial f}{\partial z} \hat{z} \\
 &= -\frac{2x \hat{x}}{(x^2+y^2+z^2)^2} - \frac{2y \hat{y}}{(x^2+y^2+z^2)^2} - \frac{2z \hat{z}}{(x^2+y^2+z^2)^2} \\
 &= -\frac{2(x \hat{x} + y \hat{y} + z \hat{z})}{(x^2+y^2+z^2)^2}
 \end{aligned}$$

$$5. \quad \because \vec{p} = 0, \quad \vec{J}_{free} = 0$$

$$\therefore \nabla \times \vec{B} = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\nabla \times \nabla \times \frac{\vec{B}}{\mu_0} = \epsilon_0 \frac{\partial}{\partial t} (\nabla \times \vec{E})$$

$$\nabla \times (\nabla \times \vec{B}) = \nabla (\nabla \cdot \vec{B}) - \nabla^2 \vec{B} = -\nabla^2 \vec{B}$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$-\nabla^2 \frac{\vec{B}}{\mu_0} = -\frac{\partial}{\partial t} \left(\frac{\partial \vec{B}}{\partial t} \right)$$

$$\nabla^2 \vec{B} = \mu_0 \epsilon_0 \frac{\partial^2}{\partial t^2} \vec{B}$$

$$6. \quad \nabla^2 \vec{E} = \mu_0 \epsilon_0 \frac{\partial^2}{\partial t^2} \vec{E}$$

$$\vec{E} = \vec{E} (\vec{r} \cdot \hat{u} - ct + \phi)$$

$$\frac{\partial^2}{\partial t^2} \vec{E} = c^2 \vec{E} (\vec{r} \cdot \hat{u} - ct + \phi)$$

$$\nabla^2 \vec{E} = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \vec{E}$$

$$\frac{\partial^2}{\partial x^2} \vec{E} = \frac{\partial^2}{\partial x^2} \vec{E} (xu_x + yu_y + zu_z - ct + \phi)$$

$$= u_x^2 \vec{E} (xu_x + yu_y + zu_z - ct + \phi)$$

$$\frac{\partial^2}{\partial y^2} \vec{E} = u_y^2 \vec{E} (xu_x + yu_y + zu_z - ct + \phi)$$

$$\frac{\partial^2}{\partial z^2} \vec{E} = u_z^2 \vec{E} (xu_x + yu_y + zu_z - ct + \phi)$$

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \vec{E} = (u_x^2 + u_y^2 + u_z^2) \vec{E}$$

$$= \vec{E}$$

$$\vec{E} = \mu_0 \epsilon_0 c^2 \vec{E} = \vec{E}$$

$$\begin{aligned}
 7. \quad \nabla^2 \vec{E} &= \nabla^2 \sum_i \vec{E}_i \\
 &= \sum_i \nabla^2 \vec{E}_i \\
 &= \sum_i \vec{E}_i
 \end{aligned}$$

$$\begin{aligned}
 \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} &= \mu_0 \epsilon_0 \frac{\partial^2}{\partial t^2} \sum_i \vec{E}_i \\
 &= \mu_0 \epsilon_0 \sum_i \frac{\partial^2}{\partial t^2} \vec{E}_i \\
 &= \mu_0 \epsilon_0 \sum_i c^2 \vec{E}_i \\
 &= \sum_i \vec{E}_i
 \end{aligned}$$

$$\text{Thus } \nabla^2 \vec{E} = \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$8. \vec{E} = E_0 \cos(\vec{k} \cdot \vec{r} - \omega t + \phi)$$

$$= (E_x \hat{x} + E_y \hat{y} + E_z \hat{z}) \cos(\underbrace{k_x x + k_y y + k_z z}_\theta - \omega t + \phi)$$

$$\nabla \times \vec{E} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x \cos \theta & E_y \cos \theta & E_z \cos \theta \end{vmatrix}$$

$$= (-E_z \sin \theta k_y + E_y \sin \theta k_z) \hat{x}$$

$$+ (-E_x \sin \theta k_z + E_z \sin \theta k_x) \hat{y}$$

$$+ (-E_y \sin \theta k_x + E_x \sin \theta k_y) \hat{z}$$

$$\frac{\partial \vec{B}}{\partial t} = \vec{k} \times \vec{E}_0 / \omega \sin \theta (-\omega)(-1)$$

$$= \vec{k} \times \vec{E}_0 \sin \theta$$

$$= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ k_x & k_y & k_z \\ E_x & E_y & E_z \end{vmatrix} \sin \theta$$

$$= (k_y E_z - k_z E_y) \hat{x} \sin \theta$$

$$+ (k_z E_x - k_x E_z) \hat{y} \sin \theta$$

$$+ (k_x E_y - k_y E_x) \hat{z} \sin \theta$$