NATIONAL UNIVERSITY OF SINGAPORE

PC5215 – NUMERICAL RECIPES WITH APPLICATIONS (Semester I: AY 2022-23)

Time Allowed: 2 Hours

INSTRUCTIONS TO STUDENTS

- 1. Write your student number on the answer book. Do not write your name.
- 2. This assessment paper contains FIVE questions and comprises THREE printed pages (including this cover page).
- 3. Students are required to answer ALL questions; each question carry equal marks.
- 4. Students should write the answers for each question on a new page.
- 5. This is a CLOSED BOOK examination.
- 6. Non-programable Calculators are allowed.

- 1. Answer briefly the following questions without derivations.
 - a. Define computational (time) complexity of an algorithm; state the computational complexity of the LU decomposition for matrix of size $N \times N$.
 - b. Give the Simpson rule for numerical integration with three equally spaced points with spacings *h*; express the truncation error of the integration formula in terms of *h*.
 - c. For a Gaussian quadrature formula with three points, what are the polynomials of the form x^n that can be integrated exactly, for integer n?
 - d. Define the symplectic algorithms for Hamiltonian dynamics.

a) The number of basic steps it takes to finish a calculation according to a given algorithm. For LU decomposition of matrix of N x N, the computational complexity is $O(N^3)$. b) $\int_0^{2h} f(x) dx = h(f_0 + 4f_1 + f_2)/3 + O(h^5)$. Here $f_i \equiv f(ih)$. c) exact for polynomials 1, x, x², ..., x⁵, and their linear combinations. d) a symplectic algorithm is such that from step n to step n+1 is a canonical transform, i.e., $\sum_j dq_j^{(n+1)} \wedge dp_j^{(n+1)} = \sum_j dq_j^{(n)} \wedge dp_j^{(n)}$. The algorithm preserves the symplectic structure of the Hamiltonian dynamics exactly.

- 2. Although the Gaussian random numbers in one dimension with a variance σ^2 and mean value a can be generated more efficiently with the Box-Muller transformation method, here we use Monte Carlo method.
 - a. The probability density p(x) of the Gaussian random number is proportional to $e^{-\frac{(x-a)^2}{2}}$. State the Matrice algorithm using this probability.
 - $e^{-\frac{(x-\alpha)}{2\sigma^2}}$. State the Metropolis algorithm using this probability.
 - b. Implement the Metropolis algorithm as a workable Python code to generate Gaussian random numbers.

a) Pick an arbitrary point x to start with. Attempt to move x to $x' = x + (2\xi-1)\Delta x$, here ξ is a uniform random number from 0 to 1, and Δx is some fixed interval, say 0.1σ . compute the ratio r = p(x')/p(x) and compare with another random number ξ_2 . If $\xi_2 < r$, use x' as the next sample. If otherwise, use x as the next sample. [In any case, we get one additional sample]. Repeat this N times. b) omitted.

- 3. Given a one variable function f(x), to determine its minimum numerically, we can first fit it to a quadratic polynomial based on the values at three points, a < c < b, with function values f(a), f(c), f(b).
 - a. Work out an explicit expression for this polynomial of degree 2.
 - b. Derive a formula for the minimum location *x* based on the result of part a.

a) We can use the Lagrange formula or Neville's algorithm, but it is simpler if we start from "first principles". Let $f(x) = \alpha x^2 + \beta x + \gamma$, Since when x = a, b, c, the function need to be f(a), f(b), f(c), respectively, we need to solve the 3 by 3 matrix equation as

 $\begin{pmatrix} a^2 & a & 1 \\ b^2 & b & 1 \\ c^2 & c & 1 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix} = \begin{pmatrix} f(a) \\ f(b) \\ f(c) \end{pmatrix}.$ The solution can be expressed via Cramer's rule as ratio

of two determinants. [Details omitted]. b) The minimum of x is $f'(x) = \frac{df}{dx} = 2\alpha x + \frac{df}{dx}$

$$\beta = 0. \quad \text{Or } x_{\min} = -\frac{\beta}{2a} = -\frac{1}{2} \frac{\begin{vmatrix} a^2 & f(a) & 1 \\ b^2 & f(b) & 1 \\ c^2 & f(c) & 1 \end{vmatrix}}{\begin{vmatrix} f(a) & a & 1 \\ f(b) & b & 1 \\ f(c) & c & 1 \end{vmatrix}} = \frac{1}{2} \frac{(b^2 - c^2)f(a) + (c^2 - a^2)f(b) + (a^2 - b^2)f(c)}{(b - c)f(a) + (c - a)f(b) + (a - b)f(c)}$$

4. A standard method to solve the time evolution of the Schrödinger equation is the Crank-Nicolson method, which is based on the approximation $\left(I + i\frac{\Delta t}{2\hbar}H\right)\Psi(t + \Delta t) = \left(I - i\frac{\Delta t}{2\hbar}H\right)\Psi(t)$ here W is a solver respect to the

 $(I - i\frac{\Delta t}{2\hbar}H)\Psi(t)$, here Ψ is a column vector of complex numbers representing the wavefunction at space points, I is the identity matrix, and H is the Hamiltonian in a discretized representation as a matrix, Δt is the time step.

- a. We say an integration scheme is order n if it is accurate to Δt^n . Determine the order of the algorithm in time step Δt , i.e., what is the integer n, such that error to the solution is $O(\Delta t^{n+1})$ in one time step?
- b. Show that the solution scheme is unitary exactly to machine precision, that is the norm $\langle \Psi | \Psi \rangle = \Psi(t + \Delta t)^{\dagger} \Psi(t + \Delta t) = \Psi(t)^{\dagger} \Psi(t)$ is invariant with respect to time steps. The dagger \dagger here denotes the Hermitian conjugate. This means that the total probability is preserved by the algorithm.

a) Let define $\alpha \equiv \frac{i\Delta tH}{\hbar}$, the Crank-Nicolson is $\left(1 + \frac{\alpha}{2}\right)\Psi(t + \Delta t) = \left(1 - \frac{\alpha}{2}\right)\Psi(t)$, or solve for $\Psi(t + \Delta t) = \left(1 + \frac{\alpha}{2}\right)^{-1}\left(1 - \frac{\alpha}{2}\right)\Psi(t)$. Taylor expand the inverse using $(1 + x)^{-1} = 1 - x + x^2 - x^3 + \cdots$, and multiply, we find $\Psi(t + \Delta t) = \left(1 - \alpha + \frac{\alpha^2}{2} - \frac{\alpha^3}{4} + \cdots\right)\Psi$. Compare this with the exact expansion of $\Psi(t + \Delta t) = e^{-\alpha}\Psi(t)$, we find the error is at α^3 (expanding the exponential gives 1/6 instead ¼ at the 3rd order). So, the algorithm is second order in Δt , error is $O(\Delta t^3)$. b) Take the Hermitian conjugate of $\Psi(t + \Delta t) = \left(1 + \frac{\alpha}{2}\right)^{-1}\left(1 - \frac{\alpha}{2}\right)\Psi(t)$, and noting that $\alpha^{\dagger} = -\alpha$, we find $\langle \Psi(t + \Delta t)|\Psi(t + \Delta t) = \langle \Psi(t) \mid \hat{O}|\Psi(t) \rangle$, the operator is $\hat{O} = \left(1 + \frac{\alpha}{2}\right)\left(1 - \frac{\alpha}{2}\right)^{-1}\left(1 + \frac{\alpha}{2}\right)^{-1}\left(1 - \frac{\alpha}{2}\right)$. These four factors commute because they are the function of a single Hamiltonian H, so we can move around and cancel them to 1.

- 5. To find an energy minimum in a molecular system with the Hamiltonian H = T + V, one can use steepest descent, here V = V(x) is the potential energy, and x is a vector of all the positions of the molecules.
 - a. If the current position is at $x^{(n)}$ at *n*-th iteration, give the iteration equation that represents a single steepest descent to the next step at n + 1.
 - b. However, in part a, we have not used the kinetic energy term $T = p^2/(2m)$, thus the steepest descent results in a slow method. How to incorporate the equations of motion of the Hamiltonian dynamics to give a better algorithm? In neural network, the resulting method is known as stochastic gradient with momentum.

a) We go in the direction of negative gradient (i.e. force) as $x^{(n+1)} = x^{(n)} - \eta \nabla V|_{x^{(n)}}$. If we perform the standard steepest descent, we do a line search to find minimum with respect to η , but in application in neural network, we just use a fixed small value of $\eta > 0$. b) we can use a method inspired by the Euler algorithm, so we update as $x^{(n+1)} = x^{(n)} + \epsilon v^{(n)}$, $v^{(n+1)} = v^{(n)} - \eta \nabla V(x^{(n)})$. This is known as stochastic gradient with momentum.