

Question

Write answers on this side of the paper only.

Do not write on either margin

$$[S1] \quad \frac{\partial}{\partial x} u = \frac{\partial}{\partial y} v = 2x - 2y, \quad \frac{\partial}{\partial y} u = -\frac{\partial}{\partial x} v = -2x - 2y$$

& $u(0,0) = 0$ imply $u(x,y) = x^2 - 2xy - y^2$.
 Compactly: $f(z) = (1+i)z^2$.

$$[S2] \quad \int_{-\infty}^{\infty} dx \delta(x^2 - 4x + 3) e^{i\pi x} = \int_{-\infty}^{\infty} dx \delta((x-1)(x-3)) e^{i\pi x}$$

$$= \int_{-\infty}^{\infty} dx \left(\frac{1}{2} \delta(x-1) + \frac{1}{2} \delta(x-3) \right) e^{i\pi x} = \frac{1}{2} e^{i\pi} + \frac{1}{2} e^{3i\pi}$$

$$= -1.$$

$$[S3] \quad \Phi = b^2 r^2 - (\vec{b} \cdot \vec{r})^2, \quad \vec{\nabla} \Phi = 2b^2 \vec{r} - 2\vec{b} \cdot \vec{r} \vec{b}$$

$$= 2\vec{b} \times (\vec{r} \times \vec{b});$$

$$\vec{\nabla}^2 \Phi = 2b^2 \vec{\nabla} \cdot \vec{r} - 2\vec{b} \cdot \vec{\nabla} \vec{b} \cdot \vec{r} = 6b^2 - 2b^2 = 4b^2.$$

$$[S4] \quad \int_S d\vec{S} \cdot \vec{\nabla} \cdot \vec{F} = \int_V (d\vec{r}) \vec{\nabla} \cdot \vec{\nabla} \cdot \vec{F}$$

$$= \int_V (d\vec{r}) [\vec{\nabla} \times (\vec{\nabla} \times \vec{F}) + \vec{\nabla}^2 \vec{F}].$$

$$[S5] \quad y \frac{dy}{dx} = x \quad \text{so} \quad \frac{d}{dx}(y^2 - x^2) = 0, \quad \text{so that}$$

$$y(x) = \sqrt{9 + x^2} \quad \text{for } y(0) = 3. \quad \text{Then}$$

$$y(4) = \sqrt{9 + 16} = 5.$$

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[L1] $F(t)$ has 2nd-order poles at $t = \pm iT$. Therefore,

$$\begin{aligned}
 f(\omega) &= \int_{-\infty}^{\infty} dt e^{i\omega t} \frac{1}{(t^2+T^2)^2} \\
 &= \int_{-\infty}^{\infty} dt e^{i|\omega|t} \frac{1}{(t^2+T^2)^2} \\
 &= 2\pi i \times \left\{ \text{residue of } \frac{e^{i|\omega|t}}{(t^2+T^2)^2} \text{ at } t=iT \right\} \\
 &= 2\pi i \left. \frac{d}{dt} \frac{e^{i|\omega|t}}{(t+iT)^2} \right|_{t=iT} \\
 &= 2\pi i \left(\frac{i|\omega| e^{-|\omega|T}}{(2iT)^2} - 2 \frac{e^{-|\omega|T}}{(2iT)^3} \right) \\
 &= \frac{2\pi i}{(2iT)^3} (2iT i|\omega| - 2) e^{-|\omega|T} \\
 &= \frac{\pi}{2T^3} (1 + |\omega|T) e^{-|\omega|T} .
 \end{aligned}$$

Verify that $f(\omega=0) = \int_{-\infty}^{\infty} dt F(t)$:

(1) $f(0) = \frac{\pi}{2T^3}$ from above

(2) $\int_{-\infty}^{\infty} dt F(t) = -\frac{1}{2T} \frac{\partial}{\partial T} \underbrace{\int_{-\infty}^{\infty} \frac{dt}{t^2+T^2}}_{= \frac{\pi}{T}} = \frac{\pi}{2T^3} .$

Indeed, $f(\omega=0)$ has the correct value.

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$$\boxed{L2} (a) (\vec{a} \times \vec{b}) \times (\vec{b} \times \vec{c}) = [(\vec{a} \times \vec{b}) \cdot \vec{c}] \vec{b}, \text{ so that}$$

$$[(\vec{a} \times \vec{b}) \times (\vec{b} \times \vec{c})] \cdot (\vec{c} \times \vec{a}) = [(\vec{a} \times \vec{b}) \cdot \vec{c}]^2.$$

$$(b) \vec{a}' = \frac{\vec{b} \times \vec{c}}{\vec{a} \cdot (\vec{b} \times \vec{c})}, \quad \vec{b}' = \frac{\vec{c} \times \vec{a}}{\vec{a} \cdot (\vec{b} \times \vec{c})}, \quad \vec{c}' = \frac{\vec{a} \times \vec{b}}{\vec{a} \cdot (\vec{b} \times \vec{c})}.$$

$$(c) \vec{a}' \hat{=} \frac{1}{2} \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}, \quad \vec{b}' \hat{=} \frac{1}{2} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}, \quad \vec{c}' \hat{=} \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}$$

either by construction according to (b)
or by inspection.

$$\boxed{L3} (a) G(t, \pi - \varphi)^* = \sum_m i^{-m} e^{-im(\pi - \varphi)} J_m(t)^*$$

$$= \sum_m i^m e^{im\varphi} J_m(t)^*$$

$$\text{so that } J_m(t)^* = J_m(t);$$

$$G(t, -\varphi) = \sum_m i^m e^{-im\varphi} J_m(t)$$

$$= \sum_m i^m e^{im\varphi} (-1)^m J_{-m}(t)$$

$$\text{so that } J_m(t) = (-1)^m J_{-m}(t);$$

$$G(-t, \pi + \varphi) = \sum_m i^m e^{im(\pi + \varphi)} J_m(-t)$$

$$= \sum_m i^m e^{im\varphi} (-1)^m J_m(-t)$$

$$\text{so that } J_m(t) = (-1)^m J_m(-t).$$

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$$\begin{aligned}
 (b) \quad \frac{\partial}{\partial \varphi} G(t, \varphi) &= -it \sin \varphi G(t, \varphi) \\
 &= \frac{t}{2} \sum_m i^m (-e^{i(m+1)\varphi} + e^{i(m-1)\varphi}) J_m(t) \\
 &= \frac{t}{2} \sum_m i^m e^{im\varphi} (i J_{m-1}(t) + i J_{m+1}(t)) \\
 &= \frac{\partial}{\partial \varphi} \sum_m i^m e^{im\varphi} J_m(t) = \sum_m i^m e^{im\varphi} im J_m(t)
 \end{aligned}$$

$$\text{gives } \frac{2m}{t} J_m(t) = J_{m-1}(t) + J_{m+1}(t);$$

$$\begin{aligned}
 \frac{\partial}{\partial t} G(t, \varphi) &= i \cos \varphi G(t, \varphi) \\
 &= \frac{1}{2} \sum_m i^m (ie^{i(m+1)\varphi} + ie^{i(m-1)\varphi}) J_m(t) \\
 &= \frac{1}{2} \sum_m i^m e^{im\varphi} (J_{m-1}(t) - J_{m+1}(t)) \\
 &= \frac{\partial}{\partial t} \sum_m i^m e^{im\varphi} J_m(t) = \sum_m i^m e^{im\varphi} \frac{\partial}{\partial t} J_m(t)
 \end{aligned}$$

$$\text{gives } 2 \frac{d}{dt} J_m(t) = J_{m-1}(t) - J_{m+1}(t).$$