

PC1134 Lecture 16

Topic

The ∇ operator, divergence and curl

Objectives

To understand the properties of the operator ∇ .
To know how to calculate divergence, curl and Laplacian in Cartesian coordinates.

Relevance

- Field and potential: potential (scalar) is easier to handle in many cases

$$\vec{E} = -\nabla\phi$$

- Being a derivative in nature, ∇ appears in many differential equations that describing physical systems and processes.

The ∇ Operator

$$\nabla \phi = \hat{x} \frac{\partial \phi}{\partial x} + \hat{y} \frac{\partial \phi}{\partial y} + \hat{z} \frac{\partial \phi}{\partial z}$$

$$\nabla \phi = \underbrace{\left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right)}_{\nabla \text{ (operator)}} \phi$$

$$\nabla = \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z}$$

∇ has no meaning by itself. It must act on a function.

Divergence

Operate ∇ on a vector?

$$\vec{V} = V_x \hat{x} + V_y \hat{y} + V_z \hat{z}$$

$$\nabla \cdot \vec{V} = \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z} \equiv \text{div} \vec{V}$$

$\nabla \cdot \vec{V}$ is the divergence of $\vec{V}$

Physically, divergence of a vector represents a source that produces divergent field lines. For example

$$\nabla \cdot \vec{E} = 4\pi\rho$$

Curl

$$\begin{aligned}\nabla \times \vec{V} &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ V_x & V_y & V_z \end{vmatrix} \\ &= \hat{x} \left(\frac{\partial V_z}{\partial y} - \frac{\partial V_y}{\partial z} \right) + \hat{y} \left(\frac{\partial V_x}{\partial z} - \frac{\partial V_z}{\partial x} \right) + \\ &\quad \hat{z} \left(\frac{\partial V_y}{\partial x} - \frac{\partial V_x}{\partial y} \right) \\ &\equiv \text{curl} \vec{V}\end{aligned}$$

$\nabla \times \vec{V}$ is the curl of $\vec{V}$

The curl of a vector represents some source that produces looped field lines or current flow. For example

$$\nabla \times \vec{H} = \frac{4\pi}{c} \vec{J}$$

Laplacian Operator

$\nabla\phi$ is a vector. $\nabla \cdot \nabla\phi = ?$

$$\begin{aligned}\nabla \cdot \nabla\phi &= \text{div grad}\phi \\&= \nabla \cdot \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \phi \\&= \frac{\partial}{\partial x} \left(\frac{\partial\phi}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial\phi}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial\phi}{\partial z} \right) \\&= \frac{\partial^2\phi}{\partial x^2} + \frac{\partial^2\phi}{\partial y^2} + \frac{\partial^2\phi}{\partial z^2}\end{aligned}$$

$$\nabla \cdot \nabla\phi = \underbrace{\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right)}_{\nabla^2 \text{ (operator)}} \phi$$

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

∇^2 is the Laplacian operator.

Examples of Laplacian Operator

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

Laplace's equation

$$\nabla^2 \phi = 0$$

Wave equation

$$\nabla^2 \phi = \frac{1}{v^2} \frac{\partial^2 \phi}{\partial t^2}$$

Diffusion equation

$$\nabla^2 \phi = \frac{1}{a^2} \frac{\partial \phi}{\partial t}$$

Schrödinger equation

$$-\frac{\hbar^2}{2m} \nabla^2 \phi + V \phi = E \phi$$

Vector Operations (Reference)

Cartesian

$$\begin{aligned}\nabla\psi &= \hat{x}\frac{\partial\psi}{\partial x} + \hat{y}\frac{\partial\psi}{\partial y} + \hat{z}\frac{\partial\psi}{\partial z} \\ \nabla \cdot \vec{A} &= \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z} \\ \nabla \times \vec{A} &= \hat{x} \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) + \hat{y} \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) + \hat{z} \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \\ \nabla^2\psi &= \frac{\partial^2\psi}{\partial x^2} + \frac{\partial^2\psi}{\partial y^2} + \frac{\partial^2\psi}{\partial z^2}\end{aligned}$$

Cylindrical

$$\begin{aligned}\nabla\psi &= \hat{e}_\rho \frac{\partial\psi}{\partial\rho} + \hat{e}_\phi \frac{1}{\rho} \frac{\partial\psi}{\partial\phi} + \hat{z} \frac{\partial\psi}{\partial z} \\ \nabla \cdot \vec{A} &= \frac{1}{\rho} \frac{\partial}{\partial\rho}(\rho A_\rho) + \frac{1}{\rho} \frac{\partial A_\phi}{\partial\phi} + \frac{\partial A_z}{\partial z} \\ \nabla \times \vec{A} &= \hat{e}_\rho \left(\frac{1}{\rho} \frac{\partial A_z}{\partial\phi} - \frac{\partial A_\phi}{\partial z} \right) + \hat{e}_\phi \left(\frac{\partial A_\rho}{\partial z} - \frac{\partial A_z}{\partial\rho} \right) + \hat{z} \frac{1}{\rho} \left(\frac{\partial}{\partial\rho}(\rho A_\phi) - \frac{\partial A_\rho}{\partial\phi} \right) \\ \nabla^2\psi &= \frac{1}{\rho} \frac{\partial}{\partial\rho} \left(\rho \frac{\partial\psi}{\partial\rho} \right) + \frac{1}{\rho^2} \frac{\partial^2\psi}{\partial\phi^2} + \frac{\partial^2\psi}{\partial z^2}\end{aligned}$$

Spherical

$$\begin{aligned}\nabla\psi &= \hat{e}_r \frac{\partial\psi}{\partial r} + \hat{e}_\theta \frac{1}{r} \frac{\partial\psi}{\partial\theta} + \hat{e}_\phi \frac{1}{r \sin\theta} \frac{\partial\psi}{\partial\phi} \\ \nabla \cdot \vec{A} &= \frac{1}{r^2} \frac{\partial}{\partial r}(r^2 A_r) + \frac{1}{r \sin\theta} \frac{\partial}{\partial\theta}(\sin\theta A_\theta) + \frac{1}{r \sin\theta} \frac{\partial A_\phi}{\partial\phi} \\ \nabla \times \vec{A} &= \hat{e}_r \frac{1}{r \sin\theta} \left[\frac{\partial}{\partial\theta}(\sin\theta A_\phi) - \frac{\partial A_\theta}{\partial\phi} \right] + \hat{e}_\theta \left[\frac{1}{r \sin\theta} \frac{\partial A_r}{\partial\phi} - \frac{1}{r} \frac{\partial}{\partial r}(r A_\phi) \right] \\ &\quad + \hat{e}_\phi \frac{1}{r} \left[\frac{\partial}{\partial r}(r A_\theta) - \frac{\partial A_r}{\partial\theta} \right] \\ \nabla^2\psi &= \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial\psi}{\partial r} \right) + \frac{1}{r^2 \sin\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial\psi}{\partial\theta} \right) + \frac{1}{r^2 \sin^2\theta} \frac{\partial^2\psi}{\partial\phi^2}\end{aligned}$$

Vector Identities (Reference)

$$\nabla \cdot \nabla \phi = \operatorname{div} \operatorname{grad} \phi = \nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2}$$

$$\nabla \times \nabla \phi = \operatorname{curl} \operatorname{grad} \phi = 0$$

$$\begin{aligned} \nabla(\nabla \cdot \vec{V}) &= \operatorname{grad} \operatorname{div} \vec{V} = \hat{x} \left(\frac{\partial^2 V_x}{\partial x^2} + \frac{\partial^2 V_y}{\partial x \partial y} + \frac{\partial^2 V_z}{\partial x \partial z} \right) + \hat{y} \left(\frac{\partial^2 V_x}{\partial x \partial y} + \frac{\partial^2 V_y}{\partial y^2} + \frac{\partial^2 V_z}{\partial y \partial z} \right) \\ &\quad + \hat{z} \left(\frac{\partial^2 V_x}{\partial x \partial z} + \frac{\partial^2 V_y}{\partial y \partial z} + \frac{\partial^2 V_z}{\partial z^2} \right) \end{aligned}$$

$$\nabla \cdot (\nabla \times \vec{V}) = \operatorname{div} \operatorname{curl} \vec{V} = 0$$

$$\nabla \times (\nabla \times \vec{V}) = \operatorname{curl} \operatorname{curl} \vec{V} = \nabla(\nabla \cdot \vec{V}) - \nabla^2 \vec{V}$$

$$\nabla \cdot (\phi \vec{V}) = \phi(\nabla \cdot \vec{V}) + \vec{V} \cdot (\nabla \phi)$$

$$\nabla \times (\phi \vec{V}) = \phi(\nabla \times \vec{V}) - \vec{V} \times (\nabla \phi)$$

$$\nabla \cdot (\vec{U} \times \vec{V}) = \vec{V} \cdot (\nabla \times \vec{U}) - \vec{U} \cdot (\nabla \times \vec{V})$$

$$\nabla \times (\vec{U} \times \vec{V}) = (\vec{V} \cdot \nabla) \vec{U} - (\vec{U} \cdot \nabla) \vec{V} - \vec{V}(\nabla \cdot \vec{U}) + \vec{U}(\nabla \cdot \vec{V})$$

$$\nabla(\vec{U} \cdot \vec{V}) = \vec{U} \times (\nabla \times \vec{V}) + (\vec{U} \cdot \nabla) \vec{V} + \vec{V} \times (\nabla \times \vec{U}) + (\vec{V} \cdot \nabla) \vec{U}$$

$$\nabla \cdot (\nabla \phi \times \nabla \psi) = 0$$